**Communication Challenge 2: Free RTOS**



A screenshot of a computer

Description automatically generated

*Circuit used: red wires are to simulate power to the component that is connected to its designated pin. The black wires are to simulate being connected to the GND pin. Each LED represents a sprinkler, and they are connected to my ESP32 as show in the above circuit.*

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*13 Oktober 2023*

# Abstract:

Real-time operating systems uses threads to implement a program that looks like it is running in “real time”. Our normal understanding of code is to use a super loop to run all our functions. These are run after each other. Using threads, we can run all these functions at the same time instead of a super loop. Threads are not completely safe and can be prone to errors or data loss. Some fixes for this include the usage of mutex and/or queues in these threads.

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# Introduction:

This report was written so we can find out more about RTOS. For the implementations below we will be using Free RTOS. As we go deeper into our implementation, we can discover the differences when we work with just threads. When we add mutex into the implementation. Finally, when we add queues into the implementation.

In short, the usage of threads is when you want a program with different functions that doesn’t run using a super loop but simultaneously with eachother. This doesn’t completely make it safe. For extra safety we can add mutexes and/or queues to make the program more thread safe and less prone to issues with synchronization.

# Procedure:

I begin by setting up my circuit for this entire challenge. See the above circuit diagram on the front page. I have set up the pins in the

|  |  |
| --- | --- |
| **COMPONENT** | **PIN** |
| LED\_1\_PIN (Sprinkler 1) | D14 |
| LED\_2\_PIN (Sprinkler 2) | D26 |
| LED\_3\_PIN (Sprinkler 3) | D21 |
| LED\_4\_PIN (Sprinkler 4) | D22 |

*Table 1: Hardware Pins*

## Threads:

Based off the requirements that were given to me, I came up with the following key conclusions:

* Each sprinkler own designated LED and a function to control turning the LEDs on and off.
* Store the operations of scenes. They are hardcoded and stored in my application.
* Make a function to execute a scene, by reading these operations of the hardcoded stored scenes and perform said operations.
* I need to test this function. First without threads.
* Make on thread, that does nothing but read the UART repeatedly. If it receives a number (in this case representing a scene), then end echo this number back to my laptop. This thread should never end.
* In that same thread when a valid number of a Scene is received from the user, start another thread that performs the operations of that Scene by calling the function to execute a scene that was defined previously.
* Make sure that that the thread ends itself in a controlled way when the Scene is done.
* Test my program with multiple Scenes running at the same time. For example: first type ‘1’ and a while later type ‘2’; Scenes 1 and 2 should then run together, which you can check by looking at the LED’s.

### Thread implementation:

Now that I knew my requirements I began to work. I first defined my LED pins to simulate the sprinklers. I then made the predefined scenes. These are hardcoded arrays with messages to simulate its behaviour. I chose to do it like this because this is one of the methods, I am most familiar with. I have made a simple function to control the state of the LED by providing it with the LED pin and the state I want the LED to be in. I defined another function to execute the scenes by providing it with the array and the size of the array. It would then perform the operations of the given array. Finally in my loop I call that function 3 times, to test all 3 scenes. The only issue I see with this implementation is that I need to implement delays in the main function for it to have my desired behaviour.

Now I will work on the thread part of this implementation.

I tested it in a way so that a user can input values. So, I tested a case, where an invalid scene is provided, an invalid character is provided and the correct one. The special problems I had was that the LEDs do turn on per scene, but they do not continue with the array. For example, if 1 was provided, the execute scene task would call the execute scene function and the execute scene function would receive array 1 and its size. The special problem that I encountered was that when I call the same scene twice, it would not execute the scene. I am assuming this is due to the lack of mutex usage. More will be researched in the mutex assignment.

## Mutex:

Based off the previous thread requirements and the ones that were now given to me, I have come with the following conclusions:

* Make the program in a way so that the scenes do not interfere with eachother if both scenes are using the same sprinkler. I need to implement this by adding one mutex per sprinkler. (Acquire the mutex before start and release mutex at the end of operation.)
* Make sure a scene doesn’t execute twice. If I use 2 scenes then they will run in parallel because, each scene has its own thread. But if I use a singular scene then the second operation of the scene must wait for the first to finish before running a second time.

Each scene must have 1 mutex. Before a thread executes the first step of a scene, it must acquire that scenes mutex and after the last step it will release it.

### Mutex implementation:

I took the previous thread assignment and from there it was rather simple what needed to be done. based on the design choices above, I have made one mutex for each LED. This will ensure that if 2 scenes use the same LED there will be no issues for the scene being called twice. It will need to take the mutex first, which it can’t since the first one has the mutex of that LED. I have done this for every LED. Now there is no more unpredictable behaviour with the LEDs if I have two scenes running with the same LED.

Now I needed to make sure that when I call a scene twice, that it will run twice. Initially, it wouldn’t run twice. The second one would be ignored. So, I thought but further investigation made me realize it is still being called, but they run simultaneously. This was a problem that I solved with the mutex for the scenes themselves. So, in my scene execution thread, I included two lines to take and give the mutex of that specific scene. I take the mutex of the scene, then call the function to execute the scene, then I give the mutex back before deleting the thread. In the end, if a scene is being called twice, it will now run the first time, then when it finishes, it will run the second time.

## Queue:

Based off the previous thread and mutex requirements and the ones that were now given to me, I have come up with the following conclusions:

* When a new thread is created to execute a Scene, the steps of that Scene should be sent to that thread through a Queue (so the thread will not access the Scene-array directly anymore but get the steps from the Queue).
* Test if my program is now completely thread safe? In other words, works correct all the time.

### Queue implementation:

Simply put I would need to repeat the same logic I did to fix the issues in the thread section of this assignment with a queue instead of a mutex. So, I took the same code I had in the thread section and started implementing based on the choices above.

I first made some changes to my UART reader thread. I define the steps (for the queue) of each scene. Depending on which scene I am using, for example if I use scene 1, I will assign the operations of scene 1 as steps. I then send these steps to the queue. Then I create my execute scene thread.

Then within this thread, I will “receive” the steps that were sent to me in the reader thread. Finally, I assign these steps into the execute scene function instead of the entire array itself. I of course still use a mutex to make sure that if a scene is executed twice, it won’t be simultaneously. With this implementation, I am sending the operations of a scene through queue steps instead of reading from the array itself.

As for an answer to the question if my program is now completely thread safe, I found the following words. Since I am using 1 queue per scene, makes the chances less of the data being manipulated by multiple scenes for example. Further use of the mutex makes it so that the operations (LED toggle in this case) make the data even less prone to being manipulated. My final answer is no, the program is not completely thread safe, because right now I am only focusing on the synchronization aspect of RTOS. If I go a bit deeper, I think I will find more information of how my program can be even more thread safe. For now, this is the safest it will get.

# Results:

Some special problems I had in my implementations were for example when I made the mutex part of the assignment, I initially made only the mutexes for LEDs. It ran fine until I tried running a scene twice, then it would only run once. So, I thought the scenes were being run simultaneously. This problem was fixed by giving each scene their own separate mutexes.

Another problem would be in the beginning I couldn’t iterate through my scenes due to me assigning the wrong values to my added pointers. Once I figured this out It was easy to iterate through the array. So, for future uses, I wouldn’t directly assign the array value to the new pointer value (only assigns the first element in the array).

My test cases were quite simple. I had an idle case, where I would execute one scene and see if it would run correctly. I would execute two scenes who use different LEDs at the same time. I would execute two scenes with the same LEDs at the same time. I would execute all 3 scenes at the same time. I executed a scene twice to see the outcome. Finally, I execute a scene twice and an additional scene as well.

I execute these test cases for all 3 implementations. Naturally in the first you will find problems that the second and third implementations fix.

All these test cases had the correct results I was expecting so I thought my implementations were a success.

# Conclusions:

What I learned from this assignment is how threading works and how I can apply both mutexes and queues to make them more efficient and be able to run either simultaneously or in order. I learned that threads are a good way to make a program execute multiple tasks at the same time (outside of a super loop), but I should be careful.

Whether I would use threads with or without a queue or a mutex highly depends on what I want my program to do.

If I am using a program that doesn’t involve the threads using shared data, I would simply just use threads without mutexes. If I am working with shared data, for example an LED in this case, I would need to apply mutexes or queues, so this data doesn’t “get lost”.

You could say using a mutex and queue are basically doing the same thing, but they are not after some research done. with mutexes you are simply giving a thread access to a shared variable, while other threads cannot access this shared variable. With queues, the threads assignments are put in a queue so when the scheduler is running, it will simply perform the tasks within the queue and not check if the threads have access to them or not.

My final thoughts would be, if possible, to just implement queues all the time if memory is not an issue, it’s a few additional lines of code that will safeguard your usage of threads. If memory is the issue but you need to implement something robust with minimal failure, then mutex would be your best choice.

## References:

[1] – Free RTOS kernel section - <https://www.freertos.org>

[2] – understand mutex and queue difference - <https://www.geeksforgeeks.org/implement-thread-safe-queue-in-c/>

[3] – understanding Free RTOS - <https://www.youtube.com/@simplyexplained>

[4] – additional information of Free RTOS - <https://www.youtube.com/@digikey>

[5] – information on queue and code implementation - <https://www.youtube.com/watch?v=pHJ3lxOoWeI>